

Re: how to solve linear curve fitting by casting it as a minimization problem

Re: how to solve linear curve fitting by casting it as a minimization problem

Source: <http://sci.tech-archive.net/Archive/sci.math.num-analysis/2008-08/msg00219.html>

- *From:* "eyh5@xxxxxxxxxxxxxxxxx" <eyh5@xxxxxxxxxxxxxxxxx>
 - *Date:* Sun, 24 Aug 2008 10:13:34 -0700 (PDT)
-

On Aug 24, 7:13 am, none <n...@xxxxxxxx> wrote:

On Sat, 23 Aug 2008 23:35:06 -0700, e...@xxxxxxxxxxxxxxxxx wrote:

Also to add: for simplicity, let's say that $GA > GB > GC > GD$.

On Aug 24, 2:31 am, "e...@xxxxxxxxxxxxxxxxx" <e...@xxxxxxxxxxxxxxxxx> wrote:

Hello,

I'm wondering if anybody can help me with this problem.
Let's first
limit ourselves to only the first quadrant of a Cartesian
coordinate
system. I have a point G that's located on the x-axis, and it's
position $(x_G, 0)$ is known ($x_G > 0$). Now, I have four points
A, B, C,
and D in this quadrant. I know these points are on a straight
line
(call it AD). This line has some arbitrary slope. I also know
the four
distances GA, GB, GC, and GD. Moreover, these four
distances are
periodically sampled, meaning that $AB = BC = CD$. However, I
do not know
the coordinates of these four points in the Cartesian system
(denoted
as (x_A, y_A) , (x_B, y_B) , (x_C, y_C) , (x_D, y_D) ,
respectively).

Re: how to solve linear curve fitting by casting it as a minimization problem

I want to find the slope of the line AD in the Cartesian system.

The way I'm thinking about doing is to cast this as a minimization problem to find the points' coordinates. That way, the trajectory slope is simply $(y_A - y_B) / (x_A - x_B)$.

However, I'm not sure how to formulate the minimization (what should be the objective function, and what should be the constraint function). Can anyone help me with this? Thanks in advance.

Is this a homework problem? To me it seems that if you know

(x_0, y_0)

slope m in $y = m x + c \rightarrow c$ can be calculated.

Simpler would be to work in a transformed coordinate so that your working space is centred on $(0, 0) \rightarrow c = 0$

and spacing $\Delta l = \text{constant} \ \& \ \text{known} \rightarrow \text{spacing } \Delta x = \text{constant} \ \& \ \text{unknown}$

then all that remains is simple trigonometry.

$\sin \theta = \Delta x / \Delta l$ would be useful.

You might want to remember that the slope, m , is given by $\Delta y / \Delta x$, and that $\tan \theta = \Delta y / \Delta x$.

Thanks for the reply. No, this is not a homework problem. It's a part of a bigger problem that I'm trying to solve in my research work.

I was able to do it in a transformed Cartesian system (with GA as the x-axis, and a y-axis perpendicular to it; this gets rid of the intercept, c , as you suggested), and trigonometry was indeed used to transform (or translate) it into the slope in the original Cartesian system. However, the solution is not accepted and my adviser is pushing to solve it by linear curve fitting. And I cannot think of another approach except doing it by means of some minimization problem, which is why I posted this message in the first place.

Also, by (x_0, y_0) , I take it you mean the coordinates of point A? Unfortunately, that knowledge is assumed unknown to me. I don't know the coordinates of any of the points A, B, C, and D. I agree that having the knowledge of A's coordinates would help a lot. But the lack

Re: how to solve linear curve fitting by casting it as a minimization problem

Re: how to solve linear curve fitting by casting it as a minimization problem

of it is what makes this problem seem so difficult.

I'm looking at the problem again and am now wondering: if all the information I know is the four distance measurements that I can measure (periodically) from a single source G on the x -axis of a global Cartesian system, does that seem to suggest that it could have an infinite number of solutions for the slope? Because we can basically rotate all four measurements simultaneously around G , and that induces infinite solutions. Would you agree?

I appreciate your further comments.

.