

# Attitude with quaternions

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Hi,

I have the following quaternions:

q1: -0.552710  
q2: -0.441034  
q3: -0.604951  
q4: 0.366106

and the attitude with YPR

yaw: -97.406°  
pitch: 20.230°  
roll: -90.000°

but I can't figure out how to get the YPR values from the Quaternions.

Can someone explain it the easy way?

Thanks a lot  
Steve

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